

TMA4275 Life time analysis

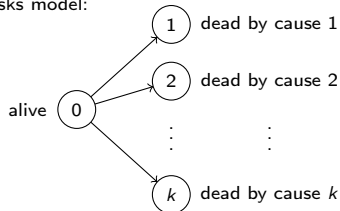
Håkon Tjelmeland

Department of Mathematical Sciences
Norwegian University of Science and Technology

Competing risks

(Reference: Section 3.4.1 in Aalen, Borgan and Gjessing, 2008)

★ Competing risks model:

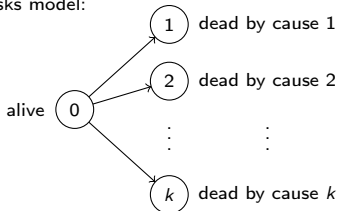


$$\begin{aligned}\hat{P}(s, t) &= \prod_{(s, t]} (\mathbb{I} + d\hat{A}(u)) \\ &= \prod_{j: s < T_j \leq t} (\mathbb{I} + \Delta\hat{A}(T_j))\end{aligned}$$

Competing risks

(Reference: Section 3.4.1 in Aalen, Borgan and Gjessing, 2008)

★ Competing risks model:



★ $P(s, t)$ has the following structure

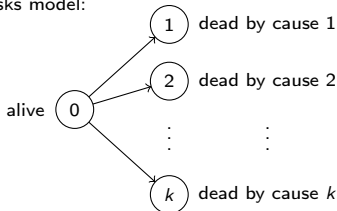
$$P(s, t) = \begin{bmatrix} P_{00}(s, t) & P_{01}(s, t) & P_{02}(s, t) & \dots & P_{0,k}(s, t) \\ 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & 0 \\ 0 & 0 & 0 & \dots & 1 \end{bmatrix}$$

$$\begin{aligned} \hat{P}(s, t) &= \prod_{(s,t]} (\mathbb{I} + d\hat{A}(u)) \\ &= \prod_{j:s < T_j \leq t} (\mathbb{I} + \Delta\hat{A}(T_j)) \end{aligned}$$

Competing risks

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- ★ Competing risks model:



- ★ $P(s, t)$ has the following structure

$$P(s, t) = \begin{bmatrix} P_{00}(s, t) & P_{01}(s, t) & P_{02}(s, t) & \dots & P_{0,k}(s, t) \\ 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & 0 \\ 0 & 0 & 0 & \dots & 1 \end{bmatrix}$$

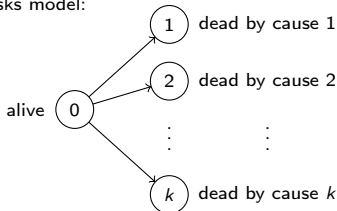
- ★ Want to find formulas for $\widehat{P}_{00}(s, t)$ and $\widehat{P}_{0h}(s, t)$

$$\begin{aligned} \widehat{P}(s, t) &= \prod_{(s,t]} (\mathbb{I} + d\widehat{A}(u)) \\ &= \prod_{j:s < T_j \leq t} (\mathbb{I} + \Delta\widehat{A}(T_j)) \end{aligned}$$

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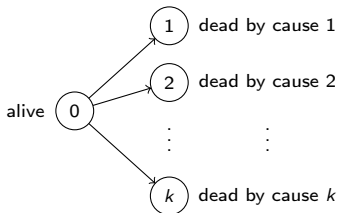
$$P(s, t) = \begin{bmatrix} P_{00}(s, t) & P_{01}(s, t) & P_{02}(s, t) & \dots & P_{0,k}(s, t) \\ 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & 0 \\ 0 & 0 & 0 & \dots & 1 \end{bmatrix}$$

- ★ Want to find formulas for $\widehat{P}_{00}(s, t)$ and $\widehat{P}_{0h}(s, t)$

- consider $k = 3$
- the factor $(\mathbb{I} + \Delta\widehat{A}(T_j))$
- product of two $(\mathbb{I} + \Delta\widehat{A}(T_j))$ factors
- product of three $(\mathbb{I} + \Delta\widehat{A}(T_j))$ factors
- “guess” on general formula
- general formula can be proved by induction

The factor $(\mathbb{I} + \Delta\hat{A}(T_j))$

★ Competing risks model



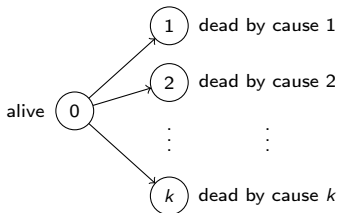
$$\begin{aligned}\hat{P}(s, t) &= \prod_{(s, t]} (\mathbb{I} + d\hat{A}(u)) \\ &= \prod_{j: s < T_j \leq t} (\mathbb{I} + \Delta\hat{A}(T_j))\end{aligned}$$

$$\begin{aligned}\hat{A}_{gh}(t) &= \int_0^t \frac{J_g(s)}{Y_g(s)} dN_{gh}(s) \\ &= \sum_{j: T_j^{gh} \leq t} \frac{\mathbf{1}}{Y_g(T_j^{gh})}\end{aligned}$$

$$\hat{A}_{gg}(t) = - \sum_{h \neq g} \hat{A}_{gh}(t)$$

The factor $(\mathbb{I} + \Delta\hat{A}(T_j))$

- ★ Competing risks model



- ★ Recall: Observe n individuals following the competing risks model

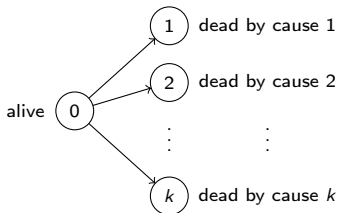
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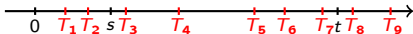
$$\hat{A}_{gg}(t) = - \sum_{h \neq g} \hat{A}_{gh}(t)$$

The factor $(\mathbb{I} + \Delta\hat{A}(T_j))$

- ★ Competing risks model



- ★ Recall: Observe n individuals following the competing risks model
- ★ Notation: $0 < T_1 < T_2 < \dots$



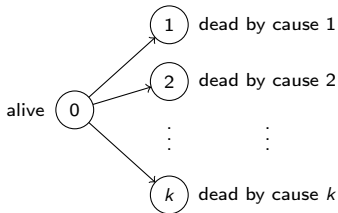
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The factor $(\mathbb{I} + \Delta\hat{A}(T_j))$

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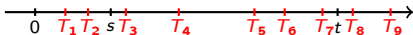


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$$\hat{A}_{gg}(t) = - \sum_{h \neq g} \hat{A}_{gh}(t)$$

- ★ Recall: Observe n individuals following the competing risks model
- ★ Notation: $0 < T_1 < T_2 < \dots$

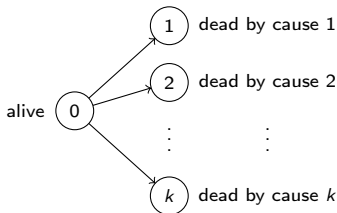


- ★ For $k = 3$, if we at time T_j observe a transition from state 0 to state 2 we have

$$\Delta\hat{A}(T_j) = \begin{bmatrix} -\frac{\mathbf{1}}{Y_0(T_j)} & 0 & \frac{\mathbf{1}}{Y_0(T_j)} & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

The factor $(\mathbb{I} + \Delta\hat{A}(T_j))$

- ★ Competing risks model

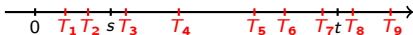


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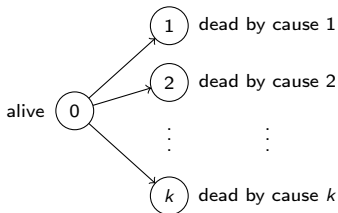


- ★ For $k = 3$, if we at time T_j observe a transition from state 0 to **some other state**, we have

$$\Delta\hat{A}(T_j) = \begin{bmatrix} -\frac{\mathbf{1}}{Y_0(T_j)} & \frac{\Delta N_{01}(T_j)}{Y_0(T_j)} & \frac{\Delta N_{02}(T_j)}{Y_0(T_j)} & \frac{\Delta N_{03}(T_j)}{Y_0(T_j)} \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

The factor $(\mathbb{I} + \Delta\hat{A}(T_j))$

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$$\begin{aligned}\hat{P}(s, t) &= \prod_{(s, t]} (\mathbb{I} + d\hat{A}(u)) \\ &= \prod_{j: s < T_j \leq t} (\mathbb{I} + \Delta\hat{A}(T_j))\end{aligned}$$

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$$\hat{A}_{gg}(t) = - \sum_{h \neq g} \hat{A}_{gh}(t)$$

- ★ Recall: Observe n individuals following the competing risks model
- ★ Notation: $0 < T_1 < T_2 < \dots$



- ★ For $k = 3$, if we at time T_j observe a transition from state 0 to **some other state**, we have

$$\mathbb{I} + \Delta\hat{A}(T_j) = \begin{bmatrix} 1 - \frac{\mathbf{1}}{Y_0(T_j)} & \frac{\Delta N_{01}(T_j)}{Y_0(T_j)} & \frac{\Delta N_{02}(T_j)}{Y_0(T_j)} & \frac{\Delta N_{03}(T_j)}{Y_0(T_j)} \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Product of two factors

$$\left(\mathbb{I} + \Delta\widehat{A}(T_j)\right) \times \left(\mathbb{I} + \Delta\widehat{A}(T_k)\right)$$

$$= \begin{bmatrix} 1 - \frac{\mathbf{1}}{Y_{\mathbf{0}}(T_j)} & \frac{\Delta N_{\mathbf{01}}(T_j)}{Y_{\mathbf{0}}(T_j)} & \frac{\Delta N_{\mathbf{02}}(T_j)}{Y_{\mathbf{0}}(T_j)} & \frac{\Delta N_{\mathbf{03}}(T_j)}{Y_{\mathbf{0}}(T_j)} \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 1 - \frac{\mathbf{1}}{Y_{\mathbf{0}}(T_k)} & \frac{\Delta N_{\mathbf{01}}(T_k)}{Y_{\mathbf{0}}(T_k)} & \frac{\Delta N_{\mathbf{02}}(T_k)}{Y_{\mathbf{0}}(T_k)} & \frac{\Delta N_{\mathbf{03}}(T_k)}{Y_{\mathbf{0}}(T_k)} \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Product of two factors

$$(\mathbb{I} + \Delta \widehat{A}(T_j)) \times (\mathbb{I} + \Delta \widehat{A}(T_k))$$

$$= \begin{bmatrix} 1 - \frac{\mathbf{1}}{Y_{\mathbf{0}}(T_j)} & \frac{\Delta N_{\mathbf{01}}(T_j)}{Y_{\mathbf{0}}(T_j)} & \frac{\Delta N_{\mathbf{02}}(T_j)}{Y_{\mathbf{0}}(T_j)} & \frac{\Delta N_{\mathbf{03}}(T_j)}{Y_{\mathbf{0}}(T_j)} \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 1 - \frac{\mathbf{1}}{Y_{\mathbf{0}}(T_k)} & \frac{\Delta N_{\mathbf{01}}(T_k)}{Y_{\mathbf{0}}(T_k)} & \frac{\Delta N_{\mathbf{02}}(T_k)}{Y_{\mathbf{0}}(T_k)} & \frac{\Delta N_{\mathbf{03}}(T_k)}{Y_{\mathbf{0}}(T_k)} \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} a(T_j) & b_1(T_j) & b_2(T_j) & b_3(T_j) \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} a(T_k) & b_1(T_k) & b_2(T_k) & b_3(T_k) \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Product of two factors

$$\left(\mathbb{I} + \Delta \widehat{A}(T_j)\right) \times \left(\mathbb{I} + \Delta \widehat{A}(T_k)\right)$$

$$= \begin{bmatrix} 1 - \frac{\mathbf{1}}{Y_{\mathbf{0}}(T_j)} & \frac{\Delta N_{\mathbf{01}}(T_j)}{Y_{\mathbf{0}}(T_j)} & \frac{\Delta N_{\mathbf{02}}(T_j)}{Y_{\mathbf{0}}(T_j)} & \frac{\Delta N_{\mathbf{03}}(T_j)}{Y_{\mathbf{0}}(T_j)} \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 1 - \frac{\mathbf{1}}{Y_{\mathbf{0}}(T_k)} & \frac{\Delta N_{\mathbf{01}}(T_k)}{Y_{\mathbf{0}}(T_k)} & \frac{\Delta N_{\mathbf{02}}(T_k)}{Y_{\mathbf{0}}(T_k)} & \frac{\Delta N_{\mathbf{03}}(T_k)}{Y_{\mathbf{0}}(T_k)} \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} a(T_j) & b_1(T_j) & b_2(T_j) & b_3(T_j) \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} a(T_k) & b_1(T_k) & b_2(T_k) & b_3(T_k) \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} a(T_j)a(T_k) & a(T_j)b_1(T_k) + b_1(T_j) & a(T_j)b_2(T_k) + b_2(T_j) & a(T_j)b_3(T_k) + b_3(T_j) \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Product of three factors

$$a(T_j) = 1 - \frac{1}{Y_0(T_j)}$$

$$b_h(T_j) = \frac{\Delta N_{0h}(T_j)}{Y_0(T_j)}$$

$$\left(\mathbb{I} + \Delta \hat{A}(T_j)\right) \times \left(\mathbb{I} + \Delta \hat{A}(T_k)\right) \times \left(\mathbb{I} + \Delta \hat{A}(T_l)\right)$$

$$= \begin{bmatrix} a(T_j)a(T_k) & a(T_j)b_1(T_k) + b_1(T_j) & a(T_j)b_2(T_k) + b_2(T_j) & a(T_j)b_3(T_k) + b_3(T_j) \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\times \begin{bmatrix} 1 - \frac{1}{Y_0(T_l)} & \frac{\Delta N_{01}(T_l)}{Y_0(T_l)} & \frac{\Delta N_{02}(T_l)}{Y_0(T_l)} & \frac{\Delta N_{03}(T_l)}{Y_0(T_l)} \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Product of three factors

$$a(T_j) = 1 - \frac{\mathbf{1}}{y_{\mathbf{0}}(T_j)}$$

$$b_h(T_j) = \frac{\Delta N_{\mathbf{0}h}(T_j)}{y_{\mathbf{0}}(T_j)}$$

$$\left(\mathbb{I} + \Delta \widehat{A}(T_j)\right) \times \left(\mathbb{I} + \Delta \widehat{A}(T_k)\right) \times \left(\mathbb{I} + \Delta \widehat{A}(T_l)\right)$$

$$= \begin{bmatrix} a(T_j)a(T_k) & a(T_j)b_1(T_k) + b_1(T_j) & a(T_j)b_2(T_k) + b_2(T_j) & a(T_j)b_3(T_k) + b_3(T_j) \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \\ \times \begin{bmatrix} a(T_l) & b_1(T_l) & b_2(T_l) & b_3(T_l) \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Product of three factors

$$a(T_j) = 1 - \frac{1}{Y_0(T_j)}$$

$$b_h(T_j) = \frac{\Delta N_{oh}(T_j)}{Y_0(T_j)}$$

$$\left(\mathbb{I} + \Delta \hat{A}(T_j) \right) \times \left(\mathbb{I} + \Delta \hat{A}(T_k) \right) \times \left(\mathbb{I} + \Delta \hat{A}(T_l) \right)$$

$$= \begin{bmatrix} a(T_j)a(T_k) & a(T_j)b_1(T_k) + b_1(T_j) & a(T_j)b_2(T_k) + b_2(T_j) & a(T_j)b_3(T_k) + b_3(T_j) \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\times \begin{bmatrix} a(T_l) & b_1(T_l) & b_2(T_l) & b_3(T_l) \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} a(T_j)a(T_k)a(T_l) & a(T_j)a(T_k)b_1(T_l) + a(T_j)b_1(T_k) + b_1(T_j) \\ 0 & 1 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} a(T_j)a(T_k)b_2(T_l) + a(T_j)b_2(T_k) + b_2(T_j) & a(T_j)a(T_k)b_3(T_l) + a(T_j)b_3(T_k) + b_3(T_j) \\ 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Product of three factors

$$a(T_j) = 1 - \frac{1}{Y_{\mathbf{0}}(T_j)}$$

$$b_h(T_j) = \frac{\Delta N_{\mathbf{0}h}(T_j)}{Y_{\mathbf{0}}(T_j)}$$

$$\left(\mathbb{I} + \Delta \hat{A}(T_j)\right) \times \left(\mathbb{I} + \Delta \hat{A}(T_k)\right) \times \left(\mathbb{I} + \Delta \hat{A}(T_l)\right)$$

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Product of three factors

$$a(T_j) = 1 - \frac{1}{Y_{\mathbf{0}}(T_j)}$$

$$b_h(T_j) = \frac{\Delta N_{\mathbf{0}h}(T_j)}{Y_{\mathbf{0}}(T_j)}$$

$$\left(\mathbb{I} + \Delta \hat{A}(T_j)\right) \times \left(\mathbb{I} + \Delta \hat{A}(T_k)\right) \times \left(\mathbb{I} + \Delta \hat{A}(T_l)\right)$$

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★ From this we see that



$$\hat{P}_{\mathbf{0}\mathbf{0}}(s, t) = \left[\prod_{j:s < T_j \leq t} \left(\mathbb{I} + \Delta \hat{A}(T_j)\right) \right]_{\mathbf{1}\mathbf{1}}$$

Product of three factors

$$a(T_j) = 1 - \frac{1}{Y_{\mathbf{0}}(T_j)}$$

$$b_h(T_j) = \frac{\Delta N_{\mathbf{0}h}(T_j)}{Y_{\mathbf{0}}(T_j)}$$

$$\left(\mathbb{I} + \Delta \widehat{A}(T_j)\right) \times \left(\mathbb{I} + \Delta \widehat{A}(T_k)\right) \times \left(\mathbb{I} + \Delta \widehat{A}(T_l)\right)$$

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★ From this we see that



$$\widehat{P}_{\mathbf{0}\mathbf{0}}(s, t) = \left[\prod_{j:s < T_j \leq t} \left(\mathbb{I} + \Delta \widehat{A}(T_j)\right) \right]_{\mathbf{1}\mathbf{1}} = \prod_{j:s < T_j \leq t} a(T_j)$$

Product of three factors

$$a(T_j) = 1 - \frac{1}{Y_0(T_j)}$$

$$b_h(T_j) = \frac{\Delta N_{0h}(T_j)}{Y_0(T_j)}$$

$$\left(\mathbb{I} + \Delta \hat{A}(T_j)\right) \times \left(\mathbb{I} + \Delta \hat{A}(T_k)\right) \times \left(\mathbb{I} + \Delta \hat{A}(T_l)\right)$$

$$= \begin{bmatrix} a(T_j)a(T_k)a(T_l) & a(T_j)a(T_k)b_1(T_l) + a(T_j)b_1(T_k) + b_1(T_l) & & & \\ 0 & 1 & & & \\ 0 & 0 & & & \\ 0 & 0 & & & \\ a(T_j)a(T_k)b_2(T_l) + a(T_j)b_2(T_k) + b_2(T_j) & a(T_j)a(T_k)b_3(T_l) + a(T_j)b_3(T_k) + b_3(T_j) & & & \\ 0 & 0 & & & \\ 1 & 0 & & & \\ 0 & 1 & & & \end{bmatrix}$$

★ From this we see that



$$\hat{P}_{00}(s, t) = \left[\prod_{j:s < T_j \leq t} \left(\mathbb{I} + \Delta \hat{A}(T_j)\right) \right]_{11} = \prod_{j:s < T_j \leq t} a(T_j) = \prod_{j:s < T_j \leq t} \left(1 - \frac{1}{Y_0(T_j)}\right)$$

Product of three factors

$$a(T_j) = 1 - \frac{1}{Y_0(T_j)}$$

$$b_h(T_j) = \frac{\Delta N_{0h}(T_j)}{Y_0(T_j)}$$

$$\left(\mathbb{I} + \Delta \hat{A}(T_j)\right) \times \left(\mathbb{I} + \Delta \hat{A}(T_k)\right) \times \left(\mathbb{I} + \Delta \hat{A}(T_l)\right)$$

$$= \begin{bmatrix} a(T_j)a(T_k)a(T_l) & a(T_j)a(T_k)b_1(T_l) + a(T_j)b_1(T_k) + b_1(T_j) & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ a(T_j)a(T_k)b_2(T_l) + a(T_j)b_2(T_k) + b_2(T_j) & a(T_j)a(T_k)b_3(T_l) + a(T_j)b_3(T_k) + b_3(T_j) & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

★ From this we see that



$$\hat{P}_{00}(s, t) = \left[\prod_{j:s < T_j \leq t} \left(\mathbb{I} + \Delta \hat{A}(T_j)\right) \right]_{\mathbf{11}} = \prod_{j:s < T_j \leq t} a(T_j) = \prod_{j:s < T_j \leq t} \left(1 - \frac{1}{Y_0(T_j)}\right)$$

$$\hat{P}_{0h}(s, t) = \left[\prod_{j:s < T_j \leq t} \left(\mathbb{I} + \Delta \hat{A}(T_j)\right) \right]_{\mathbf{1, h+1}}$$

Product of three factors

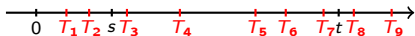
$$a(T_j) = 1 - \frac{1}{Y_0(T_j)}$$

$$b_h(T_j) = \frac{\Delta N_{0h}(T_j)}{Y_0(T_j)}$$

$$\left(\mathbb{I} + \Delta \hat{A}(T_j) \right) \times \left(\mathbb{I} + \Delta \hat{A}(T_k) \right) \times \left(\mathbb{I} + \Delta \hat{A}(T_l) \right)$$

$$= \begin{bmatrix} a(T_j)a(T_k)a(T_l) & a(T_j)a(T_k)b_1(T_l) + a(T_j)b_1(T_k) + b_1(T_j) & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ a(T_j)a(T_k)b_2(T_l) + a(T_j)b_2(T_k) + b_2(T_j) & a(T_j)a(T_k)b_3(T_l) + a(T_j)b_3(T_k) + b_3(T_j) & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 \end{bmatrix}$$

★ From this we see that



$$\hat{P}_{00}(s, t) = \left[\prod_{j:s < T_j \leq t} \left(\mathbb{I} + \Delta \hat{A}(T_j) \right) \right]_{11} = \prod_{j:s < T_j \leq t} a(T_j) = \prod_{j:s < T_j \leq t} \left(1 - \frac{1}{Y_0(T_j)} \right)$$

$$\hat{P}_{0h}(s, t) = \left[\prod_{j:s < T_j \leq t} \left(\mathbb{I} + \Delta \hat{A}(T_j) \right) \right]_{1, h+1} = \sum_{j:s < T_j \leq t} \left[\left(\prod_{k:s < T_k < T_j} a(T_k) \right) b_h(T_j) \right]$$

Proof for the formulas

- ★ Want to prove the formulas

$$\hat{P}_{00}(s, t) = \prod_{j:s < T_j \leq t} \left(1 - \frac{1}{Y_0(T_j)}\right)$$

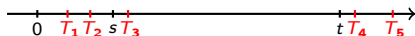
$$\hat{P}_{0h}(s, t) = \sum_{j:s < T_j \leq t} \hat{P}_{00}(s, T_{j-1}) \cdot \frac{\Delta N_{0h}(T_j)}{Y_0(T_j)}$$

- ★ Given

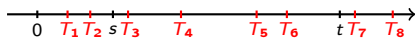
$$\hat{P}(s, t) = \prod_{j:s < T_j \leq t} (\mathbb{I} + \Delta \hat{A}(T_j))$$

- ★ Proof by induction

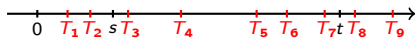
- proof formulas when only one observed transition in $(s, t]$



- assume formulas correct for k observed transition in $(s, t]$,

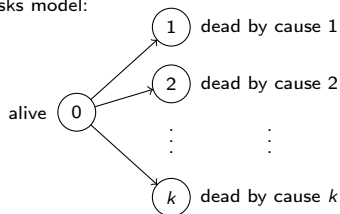


and show that then it is also correct with $k + 1$ observed transitions in $(s, t]$



Summary

- ★ Competing risks model:



- ★ Used Kaplan–Meier estimator for general Markov chain

$$\hat{P}(s, t) = \prod_{(s, t]} (\mathbb{I} + d\hat{A}(u)) = \prod_{j: s < T_j \leq t} (\mathbb{I} + \Delta\hat{A}(T_j))$$

- ★ Showed that

$$\hat{P}_{00}(s, t) = \prod_{j: s < T_j \leq t} \left(1 - \frac{1}{Y_0(T_j)} \right)$$

$$\hat{P}_{0h}(s, t) = \sum_{j: s < T_j \leq t} \hat{P}_{00}(s, T_{j-1}) \cdot \frac{\Delta N_{0h}(T_j)}{Y_0(T_j)}$$